Time-dependent linear response theory: exact and approximate formulations

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ISTPC 2017 summer school, Aussois, France, June 2017

Response properties in the time-independent regime

- In the following we shall refer to $\hat{H} = \hat{T} + \hat{W}_{ee} + \hat{V}_{ne}$ as the unperturbed Hamiltonian with ground state Ψ_0 .
- Let us introduce a perturbation operator \hat{V} with strength ε . The Hamiltonian becomes ε -dependent: $\hat{H}(\varepsilon) = \hat{H} + \varepsilon \hat{V}$.
- ullet Example: if the perturbation is a uniform electric field $oldsymbol{\mathcal{E}}$ along the z axis, then

$$\mathcal{E} = \varepsilon \, \mathbf{e}_{\mathbf{z}}$$
 and $\hat{V} = \hat{\mathbf{z}}$ where $\hat{\mathbf{z}} = \int d\mathbf{r} \, \mathbf{z} \, \hat{n}(\mathbf{r})$ \leftarrow second-quantized notation!

- Response theory is nothing but perturbation theory formulated for both exact and approximate wavefunctions.
- Let $\Psi(\varepsilon)$ denote the exact normalized ground state of $\hat{H}(\varepsilon)$ with energy $E(\varepsilon)$.
- Linear and higher-order response functions:

$$\langle \hat{V} \rangle(\varepsilon) = \langle \Psi(\varepsilon) | \hat{V} | \Psi(\varepsilon) \rangle = \langle \Psi_0 | \hat{V} | \Psi_0 \rangle + \varepsilon \langle \langle \hat{V}; \hat{V} \rangle \rangle + \frac{1}{2} \varepsilon^2 \langle \langle \hat{V}; \hat{V}, \hat{V} \rangle \rangle + \dots$$

Response properties in the time-independent regime

• In our example,

 $\langle \Psi_0 | \hat{\mathbf{z}} | \Psi_0 \rangle$ is the permanent dipole moment along the z axis

 $\langle \langle \hat{\mathbf{z}}; \hat{\mathbf{z}} \rangle \rangle = \alpha_{\mathbf{z}\mathbf{z}}$ is the static polarizability

 $\langle \langle \hat{z}; \hat{z}, \hat{z} \rangle \rangle = \beta_{zzz}$ is the static hyperpolarizability

• Hellmann–Feynman theorem:

$$\frac{\mathrm{d}E(\varepsilon)}{\mathrm{d}\varepsilon} = \left\langle \Psi(\varepsilon) \middle| \frac{\partial \hat{H}(\varepsilon)}{\partial \varepsilon} \middle| \Psi(\varepsilon) \right\rangle = \langle \hat{V} \rangle (\varepsilon)$$

• Exact response functions can be expressed as energy derivatives:

$$\langle \langle \hat{V}; \hat{V} \rangle \rangle = \left. \frac{\mathrm{d}^2 E(\varepsilon)}{\mathrm{d}\varepsilon^2} \right|_0, \qquad \langle \langle \hat{V}; \hat{V}, \hat{V} \rangle \rangle = \left. \frac{\mathrm{d}^3 E(\varepsilon)}{\mathrm{d}\varepsilon^3} \right|_0$$

Response theory for variational methods

• In variational methods, the energy is expressed as an expectation value. It depends on both the trial variational parameters λ and the perturbation strength ε :

$$E(\lambda, \varepsilon) = \langle \Psi(\lambda) | \hat{H}(\varepsilon) | \Psi(\lambda) \rangle$$

- At the HF level of approximation, λ parameterizes orbital rotations.
- At the CI level (in the basis of perturbation-independent orbitals), λ contains all the CI coefficients.
- At the MCSCF level, it contains both orbital rotation and CI coefficients.
- Stationarity condition: $\forall \varepsilon, \frac{\partial E(\lambda, \varepsilon)}{\partial \lambda} \Big|_{\lambda=\lambda(\varepsilon)} = 0$ —
- In the following, we will use parameterizations such that $\lambda(0) = 0$.
- Consequently $\lambda(\varepsilon)$ quantifies the response of the electronic wavefunction to the perturbation.

Response theory for variational methods

• The converged ground-state energy only depends on the perturbation strength:

$$\mathcal{E}(\varepsilon) = E(\lambda(\varepsilon), \varepsilon)$$

• The Hellmann–Feynman theorem remains valid for approximate variational methods:

$$\frac{\mathrm{d}\mathcal{E}(\varepsilon)}{\mathrm{d}\varepsilon} = \left[\frac{\partial \boldsymbol{\lambda}(\varepsilon)}{\partial \varepsilon}\right]^{\mathrm{T}} \underbrace{\frac{\partial E(\boldsymbol{\lambda}, \varepsilon)}{\partial \boldsymbol{\lambda}}}_{\boldsymbol{\lambda} = \boldsymbol{\lambda}(\varepsilon)} + \frac{\partial E(\boldsymbol{\lambda}, \varepsilon)}{\partial \varepsilon}\Big|_{\boldsymbol{\lambda} = \boldsymbol{\lambda}(\varepsilon)}$$

thus leading to

$$\frac{\mathrm{d}\mathcal{E}(\varepsilon)}{\mathrm{d}\varepsilon} = \left\langle \Psi\left(\mathbf{\lambda}(\varepsilon)\right) \middle| \hat{V} \middle| \Psi\left(\mathbf{\lambda}(\varepsilon)\right) \right\rangle$$

<u>Conclusion</u>: response functions obtained from variational wavefunctions can be expressed as energy derivatives.

- We denote $\{\Psi_i\}_{i=0,1,...}$ the exact orthonormal eigenvectors of the unperturbed Hamiltonian \hat{H} with energies $\{E_i\}_{i=0,1,...}$
- Exact wavefunction parameterization:

$$|\Psi(\mathbf{S})\rangle = e^{\hat{\mathbf{S}}}|\Psi_0\rangle$$

where
$$\hat{S} = \sum_{i>0} S_i (\hat{R}_i^{\dagger} - \hat{R}_i)$$
 is anti-hermitian, $\hat{R}_i^{\dagger} = |\Psi_i\rangle\langle\Psi_0|$ and $\mathbf{S} \equiv \{S_i\}_{i=1,2,...}$

- Linear response function: $\langle \langle \hat{V}; \hat{V} \rangle \rangle = \frac{\mathrm{d}^2 \mathcal{E}(\varepsilon)}{\mathrm{d}\varepsilon^2} \bigg|_{0}$ where $\mathcal{E}(\varepsilon) = E(\mathbf{S}(\varepsilon), \varepsilon)$.
- BCH expansion:

$$\frac{\mathrm{d}\mathcal{E}(\varepsilon)}{\mathrm{d}\varepsilon} = \langle \Psi_0 | e^{-\hat{\mathbf{S}}(\varepsilon)} \hat{V} e^{\hat{\mathbf{S}}(\varepsilon)} | \Psi_0 \rangle
= \langle \Psi_0 | \hat{V} | \Psi_0 \rangle + \langle \Psi_0 | [\hat{V}, \hat{\mathbf{S}}(\varepsilon)] | \Psi_0 \rangle + \frac{1}{2} \langle \Psi_0 | [[\hat{V}, \hat{\mathbf{S}}(\varepsilon)], \hat{\mathbf{S}}(\varepsilon)] | \Psi_0 \rangle + \dots$$

- Using the condition $\mathbf{S}(0) = 0$ leads to $\langle \langle \hat{V}; \hat{V} \rangle \rangle = \left\langle \Psi_0 \middle| \middle| \hat{V}, \left. \frac{\partial \hat{S}(\varepsilon)}{\partial \varepsilon} \middle|_{0} \middle| \middle| \Psi_0 \right\rangle$
- Definition: $V_i^{[1]} = \left\langle \Psi_0 \middle| \left[\hat{V}, \hat{R}_i^\dagger \hat{R}_i \right] \middle| \Psi_0 \right\rangle \quad \longleftarrow \text{component } i \text{ of the gradient property vector}$
- Usual expression for the linear response function:

$$\left\langle \langle \hat{V}; \hat{V} \rangle \right\rangle = \left[\left. \frac{\partial \mathbf{S}(\varepsilon)}{\partial \varepsilon} \right|_{0} \right]^{\mathrm{T}} V^{[1]}$$

• The linear response of the wavefunction is obtained by differentiation of the stationarity condition with respect to the perturbation strength:

$$\frac{\mathrm{d}}{\mathrm{d}\varepsilon} \left[\left. \frac{\partial E(\mathbf{S}, \varepsilon)}{\partial \mathbf{S}} \right|_{\mathbf{S} = \mathbf{S}(\varepsilon)} \right] \Big|_{0} = 0$$

• BCH expansion for the energy:

$$E(\mathbf{S}, \boldsymbol{\varepsilon}) = \langle \Psi_0 | e^{-\hat{\mathbf{S}}} \hat{H}(\boldsymbol{\varepsilon}) e^{\hat{\mathbf{S}}} | \Psi_0 \rangle$$

$$= \langle \Psi_0 | \hat{H}(\boldsymbol{\varepsilon}) | \Psi_0 \rangle + \langle \Psi_0 | [\hat{H}(\boldsymbol{\varepsilon}), \hat{\mathbf{S}}] | \Psi_0 \rangle + \frac{1}{2} \langle \Psi_0 | [[\hat{H}(\boldsymbol{\varepsilon}), \hat{\mathbf{S}}], \hat{\mathbf{S}}] | \Psi_0 \rangle + \dots$$

which leads to

$$\frac{\mathrm{d}}{\mathrm{d}\varepsilon} \left[\left. \frac{\partial E(\mathbf{S}, \varepsilon)}{\partial \mathbf{S}} \right|_{\mathbf{S} = \mathbf{S}(\varepsilon)} \right]_{0} = V^{[1]} + E^{[2]} \left[\left. \frac{\partial \mathbf{S}(\varepsilon)}{\partial \varepsilon} \right|_{0} \right] = 0$$

where the **hessian** matrix elements equal

$$E_{ij}^{[2]} = \frac{1}{2} \left\langle \Psi_0 \middle| \left[\left[\hat{H}, \hat{R}_i^{\dagger} - \hat{R}_i \right], \hat{R}_j^{\dagger} - \hat{R}_j \right] \middle| \Psi_0 \right\rangle + \frac{1}{2} \left\langle \Psi_0 \middle| \left[\left[\hat{H}, \hat{R}_j^{\dagger} - \hat{R}_j \right], \hat{R}_i^{\dagger} - \hat{R}_i \right] \middle| \Psi_0 \right\rangle$$

• In summary:

$$E^{[2]} \left[\left. \frac{\partial \mathbf{S}(\varepsilon)}{\partial \varepsilon} \right|_{0} \right] = -V^{[1]} \qquad \longleftrightarrow \qquad \left[\left. \frac{\partial \mathbf{S}(\varepsilon)}{\partial \varepsilon} \right|_{0} \right] = -\left(E^{[2]} \right)^{-1} V^{[1]}$$

$$\langle\langle \hat{V}; \hat{V} \rangle\rangle = \left[\frac{\partial \mathbf{S}(\varepsilon)}{\partial \varepsilon} \Big|_{0} \right]^{\mathrm{T}} V^{[1]} \qquad \longleftrightarrow \qquad \langle\langle \hat{V}; \hat{V} \rangle\rangle = -(V^{[1]})^{\mathrm{T}} (E^{[2]})^{-1} V^{[1]}$$

<u>Conclusion</u>: in order to compute linear response functions, the gradient property vector and the hessian matrix are needed.

EXERCISE: Show that
$$V_i^{[1]} = 2\langle \Psi_i | \hat{V} | \Psi_0 \rangle$$
, $E_{ij}^{[2]} = 2(E_i - E_0)\delta_{ij}$,

$$\left. \frac{\partial S_i(\varepsilon)}{\partial \varepsilon} \right|_0 = \frac{\langle \Psi_i | \hat{V} | \Psi_0 \rangle}{E_0 - E_i}, \quad \text{and} \quad \langle \langle \hat{V}; \hat{V} \rangle \rangle = 2 \sum_{i>0} \frac{\langle \Psi_i | \hat{V} | \Psi_0 \rangle^2}{E_0 - E_i} \quad \leftarrow \text{second-order perturbation theory!}$$

Some comments before turning to the time-dependent regime

- Let us return to (approximate) variational methods.
- $\mathbf{X} = \frac{\partial \boldsymbol{\lambda}(\varepsilon)}{\partial \varepsilon}\Big|_0$ is usually referred to as the linear response vector. Like in the exact theory, the linear response equation writes

$$E^{[2]}\mathbf{X} = -V^{[1]}$$

• In the time-dependent regime, a linear response vector will be obtained for each frequency ω . We will show in the following that the linear response equation writes

$$\left(E^{[2]} - \omega S^{[2]}\right) \mathbf{X}(\omega) = -V^{[1]}$$

• What about non-variational methods such as MP2, CC, CI with ε -dependent HF orbitals?

We, in principle, do not have a stationarity condition anymore. How to proceed with the derivation of the response equations then? What about the Hellmann–Feynman theorem?

Time-dependent linear response theory: exact and approximate formulations

- Let us denote t the non-variational parameters (CC amplitudes for example).
- For each perturbation strength, a set of equations has to be solved:

$$\mathbf{f}(\mathbf{t}(\boldsymbol{\varepsilon}), \boldsymbol{\varepsilon}) = 0$$

The non-variational energy is then determined for each perturbation strength: $\mathcal{E}(\varepsilon) = E(\mathbf{t}(\varepsilon), \varepsilon)$

$$\mathcal{E}(\varepsilon) = E(\mathbf{t}(\varepsilon), \varepsilon)$$

 $L(\mathbf{t}, \boldsymbol{\varepsilon}, \overline{\mathbf{t}}) = E(\mathbf{t}, \boldsymbol{\varepsilon}) + \overline{\mathbf{t}}^{\mathrm{T}} \mathbf{f}(\mathbf{t}, \boldsymbol{\varepsilon})$ • We introduce the Lagrangian function: and impose the following stationarity conditions:

$$\forall \varepsilon \,, \qquad \frac{\partial L(\mathbf{t}, \varepsilon, \overline{\mathbf{t}})}{\partial \overline{\mathbf{t}}} = 0 = \mathbf{f}(\mathbf{t}, \varepsilon) \qquad \text{and} \qquad \frac{\partial L(\mathbf{t}, \varepsilon, \overline{\mathbf{t}})}{\partial \mathbf{t}} = 0 = \frac{\partial E(\mathbf{t}, \varepsilon)}{\partial \mathbf{t}} + \overline{\mathbf{t}}^{\mathrm{T}} \frac{\partial \mathbf{f}(\mathbf{t}, \varepsilon)}{\partial \mathbf{t}}$$

$$\downarrow \qquad \qquad \downarrow$$

$$\mathbf{t}(\varepsilon)$$

- Note that $|\mathcal{E}(\varepsilon)| = L(\mathbf{t}(\varepsilon), \varepsilon, \overline{\mathbf{t}}(\varepsilon))$
- Hellmann–Feynman theorem: $\frac{\mathrm{d}\mathcal{E}(\varepsilon)}{\mathrm{d}\varepsilon} = \left. \frac{\partial L(\mathbf{t}, \varepsilon, \overline{\mathbf{t}})}{\partial \varepsilon} \right|_{\mathbf{t}(\varepsilon), \overline{\mathbf{t}}(\varepsilon)} = \left. \frac{\partial E(\mathbf{t}, \varepsilon)}{\partial \varepsilon} \right|_{\mathbf{t}(\varepsilon)} + \overline{\mathbf{t}}^{\mathrm{T}}(\varepsilon) \left. \frac{\partial \mathbf{f}(\mathbf{t}, \varepsilon)}{\partial \varepsilon} \right|_{\mathbf{t}(\varepsilon)}$

Time-dependent variational principle

- Time-dependent Schrödinger equation: $\hat{H}(t)|\overline{\Psi}(t)\rangle = i\frac{\mathrm{d}}{\mathrm{d}t}|\overline{\Psi}(t)\rangle$
- Alternative formulation based on a change of phase: $|\overline{\Psi}(t)\rangle = e^{-i\int_{t_0}^t Q(t)dt} |\tilde{\Psi}(t)\rangle$

$$\hat{H}(t)|\tilde{\Psi}(t)\rangle - i\frac{\mathrm{d}}{\mathrm{d}t}|\tilde{\Psi}(t)\rangle = \frac{Q(t)}{\Psi(t)}|\tilde{\Psi}(t)\rangle$$

• Connection with the Runge–Gross theorem: two local potentials that differ by a real time-dependent function lead to the same time-dependent density for a given initial wavefunction $\overline{\Psi}(t_0)$:

$$\overline{\Psi}(t_0) = \tilde{\Psi}(t_0) \quad \text{and} \quad n_{\overline{\Psi}(t)}(\mathbf{r}) = \langle \overline{\Psi}(t) | \hat{n}(\mathbf{r}) | \overline{\Psi}(t) \rangle = \langle \tilde{\Psi}(t) | \hat{n}(\mathbf{r}) | \tilde{\Psi}(t) \rangle = n_{\tilde{\Psi}(t)}(\mathbf{r})$$

• In the particular case of a time-independent Hamiltonian \hat{H} , searching for time-independent solutions $\tilde{\Psi}(t) = \tilde{\Psi}$ and Q(t) = E leads to the time-independent Schrödinger equation:

$$\hat{H}|\tilde{\Psi}\rangle = E|\tilde{\Psi}\rangle$$

Time-dependent linear response theory: exact and approximate formulations

• Returning to the time-dependent regime, Q(t) is referred to as time-dependent quasienergy.

• Since
$$\frac{\mathrm{d}}{\mathrm{d}t}\langle\overline{\Psi}(t)|\overline{\Psi}(t)\rangle=\mathrm{i}\langle\hat{H}(t)\overline{\Psi}(t)|\overline{\Psi}(t)\rangle-\mathrm{i}\langle\overline{\Psi}(t)|\hat{H}(t)|\overline{\Psi}(t)\rangle=0$$
,

if Q(t) is real then

$$\langle \tilde{\Psi}(t) | \tilde{\Psi}(t) \rangle = \langle \overline{\Psi}(t) | \overline{\Psi}(t) \rangle = \langle \tilde{\Psi}(t) | \tilde{\Psi}(t) \rangle = 1 \quad \text{and} \quad \left| \frac{Q(t)}{Q(t)} = \left\langle \tilde{\Psi}(t) | \hat{H}(t) - i \frac{\mathrm{d}}{\mathrm{d}t} | \tilde{\Psi}(t) \right\rangle \right|$$

• The real character of the time-dependent quasienergy can be explicitly connected with the conservation of the norm:

$$\frac{Q(t)^*}{Q(t)^*} = \left\langle \tilde{\Psi}(t) \left| \hat{H}(t) \right| \tilde{\Psi}(t) \right\rangle + i \left\langle \frac{d\tilde{\Psi}(t)}{dt} \left| \tilde{\Psi}(t) \right\rangle = \left\langle \tilde{\Psi}(t) \left| \hat{H}(t) \right| \tilde{\Psi}(t) \right\rangle - i \left\langle \tilde{\Psi}(t) \left| \frac{d\tilde{\Psi}(t)}{dt} \right\rangle = Q(t)$$

since
$$\left\langle \frac{\mathrm{d}\tilde{\Psi}(t)}{\mathrm{d}t} \middle| \tilde{\Psi}(t) \right\rangle = \underbrace{\frac{\mathrm{d}}{\mathrm{d}t} \left\langle \tilde{\Psi}(t) \middle| \tilde{\Psi}(t) \right\rangle}_{0} - \left\langle \tilde{\Psi}(t) \middle| \frac{\mathrm{d}\tilde{\Psi}(t)}{\mathrm{d}t} \right\rangle$$

Time-dependent variational principle

• For a given trial wavefunction $\Psi(t)$, we define the action integral as follows

$$\mathcal{A}[\Psi] = \int_{t_0}^{t_1} Q[\Psi](t) \, \mathrm{d}t \, \bigg| \qquad \text{where} \qquad Q[\Psi](t) = \frac{1}{\langle \Psi(t) | \Psi(t) \rangle} \times \left\langle \Psi(t) \left| \hat{H}(t) - \mathrm{i} \frac{\mathrm{d}}{\mathrm{d}t} \right| \Psi(t) \right\rangle$$

- Note that $Q[\tilde{\Psi}](t) = Q(t)$.
- Stationarity condition:

$$\delta \mathcal{A}[\tilde{\Psi}] = 0 \qquad \leftrightarrow \qquad \hat{H}(t)|\tilde{\Psi}(t)\rangle - i\frac{\mathrm{d}}{\mathrm{d}t}|\tilde{\Psi}(t)\rangle = Q(t)|\tilde{\Psi}(t)\rangle$$

variational formulation

non-variational formulation

<u>Proof</u>: let us consider variations $\tilde{\Psi}(t) \to \tilde{\Psi}(t) + \delta \Psi(t)$ around the exact solution $\tilde{\Psi}(t)$ with the boundary conditions $\delta \Psi(t_0) = \delta \Psi(t_1) = 0$.

Consequently, the action integral varies as follows:

$$\begin{split} \delta \mathcal{A}[\tilde{\Psi}] &= \mathcal{A}[\tilde{\Psi} + \delta \Psi] - \mathcal{A}[\tilde{\Psi}] = \int_{t_0}^{t_1} \left(Q[\tilde{\Psi} + \delta \Psi](t) - Q[\tilde{\Psi}](t) \right) \, \mathrm{d}t \\ &= \int_{t_0}^{t_1} \left\langle \delta \Psi(t) \left| \hat{H}(t) - \mathrm{i} \frac{\mathrm{d}}{\mathrm{d}t} \right| \tilde{\Psi}(t) \right\rangle \, \mathrm{d}t + \int_{t_0}^{t_1} \left\langle \tilde{\Psi}(t) \left| \hat{H}(t) - \mathrm{i} \frac{\mathrm{d}}{\mathrm{d}t} \right| \delta \Psi(t) \right\rangle \, \mathrm{d}t \\ &- \int_{t_0}^{t_1} Q(t) \left(\left\langle \delta \Psi(t) \middle| \tilde{\Psi}(t) \right\rangle + \left\langle \tilde{\Psi}(t) \middle| \delta \Psi(t) \right\rangle \right) \, \mathrm{d}t \end{split}$$
 where
$$\int_{t_0}^{t_1} \left\langle \tilde{\Psi}(t) \middle| \frac{\mathrm{d}\delta \Psi(t)}{\mathrm{d}t} \right\rangle \, \mathrm{d}t = \underbrace{\int_{t_0}^{t_1} \frac{\mathrm{d}}{\mathrm{d}t} \left\langle \tilde{\Psi}(t) \middle| \delta \Psi(t) \right\rangle \, \mathrm{d}t - \int_{t_0}^{t_1} \left\langle \frac{\mathrm{d}\tilde{\Psi}(t)}{\mathrm{d}t} \middle| \delta \Psi(t) \right\rangle \, \mathrm{d}t}_{\left[\left\langle \tilde{\Psi}(t) \middle| \delta \Psi(t) \right\rangle\right]_{t_0}^{t_1}} = 0 \end{split}$$

thus leading to

$$\delta \mathcal{A}[\tilde{\Psi}] = \int_{t_0}^{t_1} \left(\left\langle \delta \Psi(t) \left| \hat{H}(t) - i \frac{\mathrm{d}}{\mathrm{d}t} - Q(t) \right| \tilde{\Psi}(t) \right\rangle + \left\langle \delta \Psi(t) \left| \hat{H}(t) - i \frac{\mathrm{d}}{\mathrm{d}t} - Q(t) \right| \tilde{\Psi}(t) \right\rangle^* \right) \mathrm{d}t$$

Variational principle in adiabatic TD-DFT

• In time-dependent density-functional theory (TD-DFT), the physical time-dependent Hamiltonian is written as $\hat{H}(t) = \hat{T} + \hat{W}_{ee} + \int d\mathbf{r} \, v(\mathbf{r}, t) \hat{n}(\mathbf{r})$.

$$\hat{V}(t)$$
 \leftarrow time-dependent local potential operator

• In standard TD-DFT, the exact time-dependent exchange-correlation (xc) potential is approximated with the ground-state xc density-functional potential calculated at the time-dependent density (adiabatic approximation):

$$\left(\hat{T} + \hat{V}(t) + \int d\mathbf{r} \frac{\delta E_{\text{Hxc}} \left[n_{\tilde{\Phi}^{\text{KS}}(t)}\right]}{\delta n(\mathbf{r})} \hat{n}(\mathbf{r}) - i \frac{d}{dt}\right) |\tilde{\Phi}^{\text{KS}}(t)\rangle = Q^{\text{KS}}(t) |\tilde{\Phi}^{\text{KS}}(t)\rangle$$

where $n_{\tilde{\Phi}^{\mathrm{KS}}(t)}(\mathbf{r}) = \left\langle \tilde{\Phi}^{\mathrm{KS}}(t) \middle| \hat{n}(\mathbf{r}) \middle| \tilde{\Phi}^{\mathrm{KS}}(t) \right\rangle$ is an approximation to the exact physical time-dependent density $n_{\tilde{\Psi}(t)}(\mathbf{r})$.

Time-dependent linear response theory: exact and approximate formulations

EXERCISE: Show that, within the adiabatic approximation, the Kohn–Sham TD-DFT equation is equivalent to the stationarity condition $\delta A_{\rm adia}[\tilde{\Phi}^{\rm KS}] = 0$ where, for a trial wavefunction $\Psi(t)$,

$$\mathcal{A}_{\mathrm{adia}}[\Psi] = \int_{t_0}^{t_1} \frac{1}{\langle \Psi(t) | \Psi(t) \rangle} \times \left\langle \Psi(t) \left| \hat{T} + \hat{V}(t) - \mathrm{i} \frac{\mathrm{d}}{\mathrm{d}t} \right| \Psi(t) \right\rangle \, \mathrm{d}t + \int_{t_0}^{t_1} E_{\mathrm{Hxc}}[n_{\Psi(t)}] \, \mathrm{d}t$$

and
$$n_{\Psi(t)}(\mathbf{r}) = \frac{\langle \Psi(t) | \hat{n}(\mathbf{r}) | \Psi(t) \rangle}{\langle \Psi(t) | \Psi(t) \rangle}.$$

Floquet theory

- In the following we consider a periodic Hamiltonian with period T: $\hat{H}(t+T) = \hat{H}(t)$.
- $\hat{H}(t)$ can be written as a Fourier series:

$$\hat{H}(t) = \hat{T} + \hat{W}_{\text{ee}} + \hat{V}_{\text{ne}} + \sum_{x} \sum_{k=-N}^{N} e^{-\mathrm{i}\omega_k t} \varepsilon_x(\omega_k) \hat{V}_x,$$

$$\hat{\mathcal{V}}(t) \qquad \longleftarrow \text{time-dependent perturbation}$$

where $\omega_k = \frac{2\pi k}{T}$ and $\varepsilon_x(\omega_k)$ is the strength of the perturbation \hat{V}_x at frequency ω_k .

- \hat{V}_x is any kind of (hermitian) operator, not necessarily a one-electron operator even though in practice it usually is.
- In order to apply TD-DFT, \hat{V}_x should in principle be a (one-electron) local potential operator: $\hat{V}_x \to \int d\mathbf{r} \ v_x(\mathbf{r}) \hat{n}(\mathbf{r})$

Floquet theory

• Example: in the presence of a dynamic uniform electric field,

$$\mathbf{E}(t) = E_{\mathbf{x}}(t) \; \mathbf{e}_{\mathbf{x}} + E_{\mathbf{y}}(t) \; \mathbf{e}_{\mathbf{y}} + E_{\mathbf{z}}(t) \; \mathbf{e}_{\mathbf{z}} = \sum_{k=-N}^{N} e^{-\mathrm{i}\omega_{k}t} \bigg(\varepsilon_{\mathbf{x}}(\omega_{k}) \mathbf{e}_{\mathbf{x}} + \varepsilon_{\mathbf{y}}(\omega_{k}) \mathbf{e}_{\mathbf{y}} + \varepsilon_{\mathbf{z}}(\omega_{k}) \mathbf{e}_{\mathbf{z}} \bigg),$$
 the perturbation is
$$\hat{\mathcal{V}}(t) = \hat{\mathbf{r}} \cdot \mathbf{E}(t) = \hat{\mathbf{x}} \; E_{\mathbf{x}}(t) + \hat{\mathbf{y}} \; E_{\mathbf{y}}(t) + \hat{\mathbf{z}} \; E_{\mathbf{z}}(t) \quad \text{thus leading to}$$

$$\hat{\mathcal{V}}(t) = \sum_{k=-N}^{N} e^{-i\omega_k t} \left(\varepsilon_{\mathbf{x}}(\omega_k) \, \hat{\mathbf{x}} + \varepsilon_{\mathbf{y}}(\omega_k) \, \hat{\mathbf{y}} + \varepsilon_{\mathbf{z}}(\omega_k) \, \hat{\mathbf{z}} \right).$$

<u>Comment</u>: note that $\hat{\mathbf{r}}$ is written in second quantization as $\hat{\mathbf{r}} = \int \mathbf{r} \ \hat{n}(\mathbf{r}) d\mathbf{r}$ so that

$$\hat{\mathcal{V}}(t) = \int \mathbf{r} \cdot \mathbf{E}(t) \; \hat{n}(\mathbf{r}) \; d\mathbf{r} \qquad \leftarrow \text{local potential operator !}$$

Floquet theory

• Let us collect all perturbation strengths into the vector $\mathbf{\varepsilon} = \begin{bmatrix} \vdots \\ \varepsilon_x(\omega_k) \\ \vdots \end{bmatrix}$

•
$$\hat{\mathcal{V}}^{\dagger}(t) = \hat{\mathcal{V}}(t)$$
 \rightarrow $\varepsilon_x(-\omega_k)^* = \varepsilon_x(\omega_k)$

- The time-dependent wavefunction varies with the perturbation strengths: $\tilde{\Psi}(t) \equiv \tilde{\Psi}(\varepsilon, t)$
- Choice of the phase: we want the time-dependent wavefunction to become the (time-independent) ground-sate wavefunction Ψ_0 in the absence of perturbation,

$$\tilde{\Psi}(\boldsymbol{\varepsilon}=0,t)=\Psi_0.$$

• In the following, the action integral will be calculated over a period: $t_0 = 0$ and $t_1 = T$.

Response functions

• Taylor expansion of the time-dependent expectation value for the perturbation \hat{V}_x :

$$\begin{split} \langle \hat{V}_{x} \rangle (\boldsymbol{\varepsilon}, t) &= \langle \tilde{\Psi}(\boldsymbol{\varepsilon}, t) | \hat{V}_{x} | \tilde{\Psi}(\boldsymbol{\varepsilon}, t) \rangle = \\ \langle \Psi_{0} | \hat{V}_{x} | \Psi_{0} \rangle &\longleftarrow \text{zeroth order} \\ &+ \sum_{y} \sum_{k} e^{-\mathrm{i}\omega_{k}t} \varepsilon_{y}(\omega_{k}) \langle \langle \hat{V}_{x}; \hat{V}_{y} \rangle \rangle_{\omega_{k}} &\longleftarrow \text{linear response} \\ &+ \frac{1}{2} \sum_{y,z} \sum_{k,l} e^{-\mathrm{i}(\omega_{k} + \omega_{l})t} \varepsilon_{y}(\omega_{k}) \varepsilon_{z}(\omega_{l}) \langle \langle \hat{V}_{x}; \hat{V}_{y}, \hat{V}_{z} \rangle \rangle_{\omega_{k},\omega_{l}} &\longleftarrow \text{quadratic response} \\ &+ \dots \end{split}$$

• We will focuse in the following on the exact and approximate description of the linear response functions $\langle \langle \hat{V}_x; \hat{V}_y \rangle \rangle_{\omega_k}$.

Hellmann–Feynman theorem in the time-dependent regime

• The exact action integral depends both implicitly (through the time-dependent wavefunction) and explicitly (through the perturbation) on the perturbation strengths ε :

$$\left| \, \mathcal{A}(oldsymbol{arepsilon}) = \mathcal{A}\left[ilde{\Psi}(oldsymbol{arepsilon}), oldsymbol{arepsilon}
ight]
ight| \qquad \qquad ext{where}$$

$$\mathcal{A}\left[\Psi, \boldsymbol{\varepsilon}\right] = \int_0^T \frac{1}{\langle \Psi(t) | \Psi(t) \rangle} \times \left\langle \Psi(t) \left| \hat{H} + \hat{\mathcal{V}}(t) - i \frac{\mathrm{d}}{\mathrm{d}t} \right| \Psi(t) \right\rangle \mathrm{d}t$$

and $\hat{H} = \hat{T} + \hat{W}_{ee} + \hat{V}_{ne}$

 \leftarrow unperturbed Hamiltonian

ullet $\Psi(oldsymbol{arepsilon},t)$ is determined from the variational principle: thus leading to the Hellmann–Feynman theorem

$$orall oldsymbol{arepsilon}, \;\; \delta \mathcal{A} \left[ilde{\Psi}(oldsymbol{arepsilon}), oldsymbol{arepsilon}
ight] = 0$$

$$\frac{\mathrm{d}\mathcal{A}(\boldsymbol{\varepsilon})}{\mathrm{d}\varepsilon_x(\omega_k)} = \left. \frac{\partial \mathcal{A}[\Psi, \boldsymbol{\varepsilon}]}{\partial \varepsilon_x(\omega_k)} \right|_{\Psi = \Psi(\boldsymbol{\varepsilon})}$$

Time-dependent linear response theory: exact and approximate formulations

•
$$\frac{\partial \hat{\mathcal{V}}(t)}{\partial \varepsilon_x(\omega_k)} = e^{-i\omega_k t} \hat{V}_x \longrightarrow \frac{\mathrm{d}\mathcal{A}(\boldsymbol{\varepsilon})}{\mathrm{d}\varepsilon_x(\omega_k)} = \int_0^T e^{-i\omega_k t} \langle \hat{V}_x \rangle(\boldsymbol{\varepsilon}, t) \,\mathrm{d}t$$

• Important consequence: response functions can be expressed as action integral derivatives!

• zeroth order:
$$\frac{\mathrm{d}\mathcal{A}(\boldsymbol{\varepsilon})}{\mathrm{d}\varepsilon_x(\omega_k)}\Big|_0 = \int_0^T e^{-\mathrm{i}\omega_k t} \langle \Psi_0|\hat{V}_x|\Psi_0\rangle \,\mathrm{d}t = T\langle \Psi_0|\hat{V}_x|\Psi_0\rangle\delta(\omega_k)$$
 thus leading to

$$\langle \Psi_0 | \hat{V}_x | \Psi_0 \rangle = \frac{1}{T} \left. \frac{\mathrm{d} \mathcal{A}(\boldsymbol{\varepsilon})}{\mathrm{d} \varepsilon_x(0)} \right|_0$$

• Linear response:

$$\frac{\mathrm{d}^2 \mathcal{A}(\boldsymbol{\varepsilon})}{\mathrm{d}\varepsilon_y(\omega_l)\mathrm{d}\varepsilon_x(\omega_k)}\bigg|_0 = \int_0^T e^{-\mathrm{i}(\omega_k + \omega_l)t} \langle \langle \hat{V}_x; \hat{V}_y \rangle \rangle_{\omega_l} \, \mathrm{d}t = T \langle \langle \hat{V}_x; \hat{V}_y \rangle \rangle_{\omega_l} \delta(\omega_k + \omega_l)$$

thus leading to

$$\left| \langle \langle \hat{V}_x; \hat{V}_y \rangle \rangle_{\omega_l} = \frac{1}{T} \left. \frac{\mathrm{d}^2 \mathcal{A}(\boldsymbol{\varepsilon})}{\mathrm{d} \varepsilon_y(\omega_l) \mathrm{d} \varepsilon_x(-\omega_l)} \right|_0 \right|$$

Some general statements before deriving more equations ...

- (Linear) response functions can be expressed as derivatives of the action integral with respect to the perturbation strengths.
- Such a formulation is convenient for deriving exact and approximate expressions for the response functions. In the latter case, non-variational methods such as Coupled-Cluster (CC) theory can also be considered (Lagrangian formalism).
- Various (approximate) parameterizations of the time-dependent wavefunction $\tilde{\Psi}(\boldsymbol{\varepsilon},t)$ will lead to various response theories.
- Variational methods such as HF and MCSCF will be considered in the following.
- Adiabatic TD-DFT equations (Casida equations) can be obtained similarly.
- TD linear response CC theory can be derived by means of a Lagrangian formalism (in analogy with time-independent CC response theory).

Time-dependent linear response theory: exact and approximate formulations

• In the exact theory,

$$\langle \langle \hat{V}_x; \hat{V}_y \rangle \rangle_{\omega_l} = \frac{1}{T} \int_0^T e^{i\omega_l t} \left[\left\langle \underbrace{\frac{\partial \tilde{\Psi}(\boldsymbol{\varepsilon}, t)}{\partial \varepsilon_y(\omega_l)}}_{\boldsymbol{\omega}} \right|_0 \right| \hat{V}_x \left| \Psi_0 \right\rangle + \left\langle \left| \frac{\partial \tilde{\Psi}(\boldsymbol{\varepsilon}, t)}{\partial \varepsilon_y(\omega_l)} \right|_0 \left| \hat{V}_x \right| \Psi_0 \right\rangle^* \right] dt$$

linear response of the wavefunction (first order in perturbation theory)

- Note that, in the static case, the action integral over T becomes the energy. Consequently, the standard second-order energy correction $\langle \Psi_0 | \hat{V}_x | \Psi^{(1)} \rangle$ is recovered.
- Linear and higher-order responses of the wavefunction are obtained through differentiations of the stationarity condition with respect to the perturbation strengths:

$$\frac{\mathrm{d}}{\mathrm{d}\varepsilon_{y}(\omega_{l})} \left(\delta \mathcal{A} \left[\tilde{\Psi}(\boldsymbol{\varepsilon}), \boldsymbol{\varepsilon} \right] \right) \bigg|_{0} = 0 \longrightarrow \frac{\partial \tilde{\Psi}(\boldsymbol{\varepsilon}, t)}{\partial \varepsilon_{y}(\omega_{l})} \bigg|_{0}$$

Wavefunction parameterization

• **Double-exponential** parameterization of a trial wavefunction:

$$|\Psi(t)\rangle = e^{i\hat{\kappa}(t)}e^{i\hat{S}(t)}|\Psi_0\rangle$$

- The hermitian operators $\hat{\kappa}(t)$ and $\hat{S}(t)$ ensure **rotations** in the orbital and configuration spaces, respectively.
- Fourier series:

$$\hat{\kappa}(t) = \sum_{l,i} e^{-\mathrm{i}\omega_l t} \kappa_i(\omega_l) \hat{q}_i^\dagger + e^{-\mathrm{i}\omega_l t} \kappa_i^*(-\omega_l) \hat{q}_i \qquad \text{where} \qquad \hat{q}_i^\dagger = \hat{E}_{pq} \quad \text{ and } \quad p > q,$$

$$\hat{S}(t) = \sum_{l,i} e^{-i\omega_l t} S_i(\omega_l) \hat{R}_i^{\dagger} + e^{-i\omega_l t} S_i^*(-\omega_l) \hat{R}_i \qquad \text{where} \qquad \hat{R}_i^{\dagger} = |i\rangle \langle \Psi_0|.$$

• The time-dependent wavefunction is fully determined from the Fourier component vectors

$$oldsymbol{\Lambda}(\omega_l) = egin{bmatrix} \kappa_i(\omega_l) \\ S_i(\omega_l) \\ \kappa_i^*(-\omega_l) \\ S_i^*(-\omega_l) \end{bmatrix}$$
 \times to be used as **variational parameters**!

Such a parameterization will enable us to derive

• an **exact response theory** when

$$\hat{\kappa}(t) = 0$$
 and $\hat{R}_i^{\dagger} = |\Psi_i\rangle\langle\Psi_0|$ with $i > 0$ and $\forall k \geq 0$, $\hat{H}|\Psi_k\rangle = E_k|\Psi_k\rangle$.

• **HF response theory** (RPA) when

$$\hat{S}(t) = 0$$
, $\Psi_0 \to \Phi_0$ (HF determinant),

and $\hat{q}_i^{\dagger} \to \hat{E}_{aj}$ (single excitation from the occupied j orbital to the unoccupied a orbital)

• MCSCF response theory when

$$\Psi_0 \to \Psi^{(0)}$$
 (MCSCF wavefunction), $\hat{R}_i^{\dagger} \to |\det_i\rangle\langle\Psi^{(0)}|$ (rotation within the active space), and $\hat{q}_i^{\dagger} \to \hat{E}_{uj}, \hat{E}_{aj}, \hat{E}_{au}$.

Response properties from adiabatic TD-DFT

The HF parameterization enables also to derive standard TD-DFT response equations:

• for **pure exchange** functionals, the action integral expression to be used is

$$\mathcal{A}_{\text{adia}}\left[\Psi,\boldsymbol{\varepsilon}\right] = \int_0^T \left\langle \Psi(t) \left| \hat{T} + \hat{V}_{\text{ne}} + \hat{\mathcal{V}}(t) - i \frac{\mathrm{d}}{\mathrm{d}t} \right| \Psi(t) \right\rangle \mathrm{d}t + \int_0^T E_{\text{Hxc}}[n_{\Psi(t)}] \, \mathrm{d}t$$

• for **hybrid exchange** functionals, the action integral expression to be used is

$$\mathcal{A}_{\text{adia}}^{\alpha} \left[\Psi, \boldsymbol{\varepsilon} \right] = \int_{0}^{T} \left\langle \Psi(t) \left| \hat{T} + \hat{V}_{\text{ne}} + \alpha \hat{W}_{\text{ee}} + \hat{\mathcal{V}}(t) - i \frac{d}{dt} \right| \Psi(t) \right\rangle dt + \int_{0}^{T} (1 - \alpha) E_{\text{Hx}}[n_{\Psi(t)}] dt + \int_{0}^{T} E_{\text{c}}[n_{\Psi(t)}] dt$$

• For the sake of generality, we will derive, in the following, response equations for a mixed wavefunction/density-functional variational action integral:

$$\mathcal{A}\left[\Psi,\boldsymbol{\varepsilon}\right] \to \mathcal{A}_{\text{var}}\left[\Psi,\boldsymbol{\varepsilon}\right] = \int_0^T \left\langle \Psi(t) \left| \hat{\mathcal{H}} + \hat{\mathcal{V}}(t) - i \frac{\mathrm{d}}{\mathrm{d}t} \right| \Psi(t) \right\rangle \mathrm{d}t + \int_0^T \overline{E}_{\mathrm{Hxc}}[n_{\Psi(t)}] \, \mathrm{d}t \right|$$

Hellmann–Feynman theorem for time-dependent variational methods

$$\mathcal{A}_{\text{var}}\left[\Psi, \boldsymbol{\varepsilon}\right] = \int_{0}^{T} \left\langle \Psi(t) \left| \hat{\mathcal{H}} + \hat{\mathcal{V}}(t) - i \frac{\mathrm{d}}{\mathrm{d}t} \right| \Psi(t) \right\rangle \mathrm{d}t + \int_{0}^{T} \overline{E}_{\text{Hxc}}[n_{\Psi(t)}] \, \mathrm{d}t$$

- Let us keep in mind that the wavefunction Ψ is determined from the vector $\mathbf{\Lambda} \equiv \{\mathbf{\Lambda}(\omega_l)\}_l$
- The action integral will therefore be denoted $A_{\text{var}}(\Lambda, \varepsilon)$ in the following.
- For any perturbation strength ε , $\Lambda(\varepsilon)$ is obtained from the stationarity condition:

$$\forall \boldsymbol{\varepsilon}, \quad \left. \frac{\partial \mathcal{A}_{\mathrm{var}}(\boldsymbol{\Lambda}, \boldsymbol{\varepsilon})}{\partial \boldsymbol{\Lambda}} \right|_{\boldsymbol{\Lambda} = \boldsymbol{\Lambda}(\boldsymbol{\varepsilon})} = 0$$

• Consequently, the Hellmann-Feynman theorem is fulfilled for the variational action integral $\mathcal{A}_{\mathrm{var}}(\varepsilon) = \mathcal{A}_{\mathrm{var}}(\Lambda(\varepsilon), \varepsilon)$, exactly like in the exact theory:

$$\left. rac{\mathrm{d} \mathcal{A}_{\mathrm{var}}(oldsymbol{arepsilon})}{\mathrm{d} oldsymbol{arepsilon}} = \left. rac{\partial \mathcal{A}_{\mathrm{var}}(oldsymbol{\Lambda}, oldsymbol{arepsilon})}{\partial oldsymbol{arepsilon}}
ight|_{oldsymbol{\Lambda} = oldsymbol{\Lambda}(oldsymbol{arepsilon})}$$

Linear response functions

• Therefore, in analogy with the exact theory, $\langle \langle \hat{V}_x; \hat{V}_y \rangle \rangle_{\omega_l} = \frac{1}{T} \left. \frac{\mathrm{d}^2 \mathcal{A}_{\mathrm{var}}(\boldsymbol{\varepsilon})}{\mathrm{d}\varepsilon_y(\omega_l) \mathrm{d}\varepsilon_x(-\omega_l)} \right|_0$ where

$$\frac{d\mathcal{A}_{\text{var}}(\boldsymbol{\varepsilon})}{d\boldsymbol{\varepsilon}_{x}(-\omega_{l})} = \int_{0}^{T} e^{i\omega_{l}t} \left\langle \Psi(t) \left| \hat{V}_{x} \right| \Psi(t) \right\rangle dt$$

$$= \int_{0}^{T} e^{i\omega_{l}t} \left\langle \Psi_{0} \left| e^{-i\hat{\boldsymbol{S}}(t)} e^{-i\hat{\boldsymbol{\kappa}}(t)} \hat{V}_{x} e^{i\hat{\boldsymbol{\kappa}}(t)} e^{i\hat{\boldsymbol{S}}(t)} \right| \Psi_{0} \right\rangle dt$$

thus leading to

$$\frac{d\mathcal{A}_{\text{var}}(\boldsymbol{\varepsilon})}{d\varepsilon_{x}(-\omega_{l})} = \int_{0}^{T} e^{i\omega_{l}t} \left[\left\langle \Psi_{0} \middle| \hat{V}_{x} \middle| \Psi_{0} \right\rangle + i \left\langle \Psi_{0} \middle| \left[\hat{V}_{x}, \hat{\boldsymbol{\kappa}}(t) \right] \middle| \Psi_{0} \right\rangle + i \left\langle \Psi_{0} \middle| \left[\hat{V}_{x}, \hat{\boldsymbol{S}}(t) \right] \middle| \Psi_{0} \right\rangle + \dots \right] dt$$

$$= T\delta(\omega_{l}) \left\langle \Psi_{0} \middle| \hat{V}_{x} \middle| \Psi_{0} \right\rangle + i T V_{x}^{[1]\dagger} \boldsymbol{\Lambda}(\omega_{l}) + \dots$$

Linear response functions

where the gradient property vector is defined as

$$V_x^{[1]} = \begin{bmatrix} \langle \Psi_0 | [\hat{q}_i, \hat{V}_x] | \Psi_0 \rangle \\ \langle \Psi_0 | [\hat{R}_i, \hat{V}_x] | \Psi_0 \rangle \\ \langle \Psi_0 | [\hat{q}_i^{\dagger}, \hat{V}_x] | \Psi_0 \rangle \\ \langle \Psi_0 | [\hat{R}_i^{\dagger}, \hat{V}_x] | \Psi_0 \rangle \end{bmatrix}$$

Conclusion:

$$\langle\langle \hat{V}_x; \hat{V}_y \rangle\rangle_{\omega_l} = \mathrm{i} \left. V_x^{[1]\dagger} \left. \frac{\partial \mathbf{\Lambda}(\omega_l)}{\partial \varepsilon_y(\omega_l)} \right|_0$$

We now need to derive the linear response equation that is fulfilled by the linear response vector

$$\mathbf{X}_{y}(\omega_{l}) = \left. \frac{\partial \mathbf{\Lambda}(\omega_{l})}{\partial \varepsilon_{y}(\omega_{l})} \right|_{0}.$$

$$\frac{\mathrm{d}}{\mathrm{d}\varepsilon_{y}(\omega_{m})} \left[\left. \frac{\partial \mathcal{A}_{\mathrm{var}}(\boldsymbol{\Lambda}, \boldsymbol{\varepsilon})}{\partial \boldsymbol{\Lambda}^{\dagger}(-\omega_{l})} \right|_{\boldsymbol{\Lambda} = \boldsymbol{\Lambda}(\boldsymbol{\varepsilon})} \right]_{0} = 0$$

where

$$\mathcal{A}_{\mathrm{var}}\left[oldsymbol{\Lambda},oldsymbol{arepsilon}
ight]$$

$$\underbrace{\int_{0}^{T} \left\langle \Psi(t) \middle| \hat{\mathcal{H}} \middle| \Psi(t) \right\rangle dt}_{\mathcal{A}_{\hat{\mathcal{H}}} \left[\mathbf{\Lambda} \right]} + \underbrace{\int_{0}^{T} \overline{E}_{\mathrm{Hxc}}[n_{\Psi(t)}] dt}_{\mathcal{A}_{\hat{\mathcal{V}}} \left[\mathbf{\Lambda} \right]} + \underbrace{\int_{0}^{T} \left\langle \Psi(t) \middle| \hat{\mathcal{V}}(t) \middle| \Psi(t) \right\rangle dt}_{\mathcal{A}_{\hat{\mathcal{V}}} \left[\mathbf{\Lambda}, \boldsymbol{\varepsilon} \right]} + \underbrace{\int_{0}^{T} \left\langle \Psi(t) \middle| -\mathrm{i} \frac{\mathrm{d}}{\mathrm{d}t} \middle| \Psi(t) \right\rangle dt}_{\mathcal{A}_{\mathrm{d}/\mathrm{d}t} \left[\mathbf{\Lambda} \right]}$$

•
$$\mathcal{A}_{\hat{\mathcal{V}}}\left[\mathbf{\Lambda}, \boldsymbol{\varepsilon}\right] = \sum_{x} \sum_{k=-N}^{N} \sum_{p} \varepsilon_{x}(\omega_{k}) \left[T\delta(\omega_{k}) \left\langle \Psi_{0} \left| \hat{V}_{x} \right| \Psi_{0} \right\rangle + iT\delta(\omega_{k} + \omega_{p}) \underbrace{V_{x}^{[1]\dagger} \mathbf{\Lambda}(\omega_{p})}_{L^{2}} + \dots \right]$$

$$\frac{1}{2} V_{x}^{[1]\dagger} \mathbf{\Lambda}(\omega_{p}) - \frac{1}{2} \mathbf{\Lambda}^{\dagger}(-\omega_{p}) V_{x}^{[1]}$$

$$\longrightarrow \frac{\mathrm{d}}{\mathrm{d}\varepsilon_{y}(\omega_{m})} \left[\left. \frac{\partial \mathcal{A}_{\hat{\mathcal{V}}}(\boldsymbol{\Lambda}, \boldsymbol{\varepsilon})}{\partial \boldsymbol{\Lambda}^{\dagger}(-\omega_{l})} \right|_{\boldsymbol{\Lambda} = \boldsymbol{\Lambda}(\boldsymbol{\varepsilon})} \right]_{0} = -\frac{\mathrm{i}T}{2} \delta(\omega_{m} + \omega_{l}) V_{y}^{[1]}$$

EXERCISE: Let
$$\hat{f}(x,t) = e^{-x\hat{A}(t)} \frac{\mathrm{d}}{\mathrm{d}t} e^{x\hat{A}(t)}$$
.

Show that
$$\hat{f}(1,t) = \int_0^1 \frac{\partial \hat{f}(x,t)}{\partial x} dx = \frac{d\hat{A}(t)}{dt} + \frac{1}{2} \left[\frac{d\hat{A}(t)}{dt}, \hat{A}(t) \right] + \dots$$

• Using

$$e^{-\mathrm{i}\hat{S}(t)}e^{-\mathrm{i}\hat{\kappa}(t)}\frac{\mathrm{d}}{\mathrm{d}t}\left(e^{\mathrm{i}\hat{\kappa}(t)}e^{\mathrm{i}\hat{S}(t)}\right) = e^{-\mathrm{i}\hat{S}(t)}\left(e^{-\mathrm{i}\hat{\kappa}(t)}\frac{\mathrm{d}}{\mathrm{d}t}e^{\mathrm{i}\hat{\kappa}(t)}\right)e^{\mathrm{i}\hat{S}(t)} + e^{-\mathrm{i}\hat{S}(t)}\frac{\mathrm{d}}{\mathrm{d}t}e^{\mathrm{i}\hat{S}(t)}$$

leads to

$$\mathcal{A}_{\mathrm{d}/\mathrm{d}t} \left[\mathbf{\Lambda} \right] = \int_{0}^{T} \left\langle \Psi_{0} \middle| \frac{\mathrm{d}\hat{\kappa}(t)}{\mathrm{d}t} + \frac{\mathrm{d}\hat{S}(t)}{\mathrm{d}t} \middle| \Psi_{0} \right\rangle \mathrm{d}t$$

$$+\mathrm{i}\int_0^T \left\langle \Psi_0 \left| \frac{1}{2} \left[\frac{\mathrm{d}\hat{\kappa}(t)}{\mathrm{d}t}, \hat{\kappa}(t) \right] + \frac{1}{2} \left[\frac{\mathrm{d}\hat{S}(t)}{\mathrm{d}t}, \hat{S}(t) \right] + \left[\frac{\mathrm{d}\hat{\kappa}(t)}{\mathrm{d}t}, \hat{S}(t) \right] \middle| \Psi_0 \right\rangle \mathrm{d}t + \dots$$

$$\longrightarrow \frac{\mathrm{d}}{\mathrm{d}\varepsilon_{y}(\omega_{m})} \left[\left. \frac{\partial \mathcal{A}_{\mathrm{d}/\mathrm{d}t} \left[\mathbf{\Lambda} \right]}{\partial \mathbf{\Lambda}^{\dagger} \left(-\omega_{l} \right)} \right|_{\mathbf{\Lambda} = \mathbf{\Lambda}(\boldsymbol{\varepsilon})} \right]_{0} = \frac{T}{2} \omega_{l} \left. S^{[2]} \left. \frac{\partial \mathbf{\Lambda} \left(-\omega_{l} \right)}{\partial \varepsilon_{y}(\omega_{m})} \right|_{0}$$

where

$$S^{[2]} = \begin{bmatrix} \Sigma & \Delta \\ -\Delta^* & -\Sigma^* \end{bmatrix},$$

$$\Sigma = \begin{bmatrix} \langle \Psi_0 | [\hat{q}_i, \hat{q}_j^{\dagger}] | \Psi_0 \rangle & \langle \Psi_0 | [\hat{q}_i, \hat{R}_j^{\dagger}] | \Psi_0 \rangle \\ \langle \Psi_0 | [\hat{R}_i, \hat{q}_j^{\dagger}] | \Psi_0 \rangle & \langle \Psi_0 | [\hat{R}_i, \hat{R}_j^{\dagger}] | \Psi_0 \rangle \end{bmatrix},$$

$$\Delta = \begin{bmatrix} \langle \Psi_0 | [\hat{q}_i, \hat{q}_j] | \Psi_0 \rangle & \langle \Psi_0 | [\hat{q}_i, \hat{R}_j] | \Psi_0 \rangle \\ \langle \Psi_0 | [\hat{R}_i, \hat{q}_j] | \Psi_0 \rangle & \langle \Psi_0 | [\hat{R}_i, \hat{R}_j] | \Psi_0 \rangle \end{bmatrix}.$$

• Using the BCH expansion leads to

$$\mathcal{A}_{\hat{\mathcal{H}}}\left[\mathbf{\Lambda}\right] = \int_{0}^{T} \left\langle \Psi_{0} \middle| \hat{\mathcal{H}} + i \left[\hat{\mathcal{H}}, \hat{\boldsymbol{\kappa}}(t) \right] + i \left[\hat{\mathcal{H}}, \hat{\boldsymbol{S}}(t) \right] \middle| \Psi_{0} \right\rangle dt$$

$$-\int_0^T \left\langle \Psi_0 \middle| \frac{1}{2} \left[\left[\hat{\mathcal{H}}, \hat{\kappa}(t) \right], \hat{\kappa}(t) \right] + \frac{1}{2} \left[\left[\hat{\mathcal{H}}, \hat{S}(t) \right], \hat{S}(t) \right] + \left[\left[\hat{\mathcal{H}}, \hat{\kappa}(t) \right], \hat{S}(t) \right] \middle| \Psi_0 \right\rangle dt + \dots$$

$$\longrightarrow \frac{\mathrm{d}}{\mathrm{d}\varepsilon_{y}(\omega_{m})} \left[\left. \frac{\partial \mathcal{A}_{\hat{\mathcal{H}}} \left[\mathbf{\Lambda} \right]}{\partial \mathbf{\Lambda}^{\dagger} \left(-\omega_{l} \right)} \right|_{\mathbf{\Lambda} = \mathbf{\Lambda}(\boldsymbol{\varepsilon})} \right]_{0} = \frac{T}{2} \left. E^{[2]} \left. \frac{\partial \mathbf{\Lambda} \left(-\omega_{l} \right)}{\partial \varepsilon_{y}(\omega_{m})} \right|_{0}$$

where

$$E^{[2]} = \begin{bmatrix} A & B \\ B^* & A^* \end{bmatrix},$$

$$A = \begin{bmatrix} \langle \Psi_0 | [\hat{q}_i, [\hat{\mathcal{H}}, \hat{q}_j^{\dagger}]] | \Psi_0 \rangle & \langle \Psi_0 | [[\hat{q}_i, \hat{\mathcal{H}}], \hat{R}_j^{\dagger}] | \Psi_0 \rangle \\ \langle \Psi_0 | [\hat{R}_i, [\hat{\mathcal{H}}, \hat{q}_j^{\dagger}]] | \Psi_0 \rangle & \langle \Psi_0 | [\hat{R}_i, [\hat{\mathcal{H}}, \hat{R}_j^{\dagger}]] | \Psi_0 \rangle \end{bmatrix},$$

$$B = \begin{bmatrix} \langle \Psi_0 | [\hat{q}_i, [\hat{\mathcal{H}}, \hat{q}_j]] | \Psi_0 \rangle & \langle \Psi_0 | [[\hat{q}_i, \hat{\mathcal{H}}], \hat{R}_j] | \Psi_0 \rangle \\ \langle \Psi_0 | [\hat{R}_i, [\hat{\mathcal{H}}, \hat{q}_j]] | \Psi_0 \rangle & \langle \Psi_0 | [\hat{R}_i, [\hat{\mathcal{H}}, \hat{R}_j]] | \Psi_0 \rangle \end{bmatrix}.$$

• DFT-type contribution:

$$\frac{\mathrm{d}}{\mathrm{d}\varepsilon_{y}(\omega_{m})} \left[\left. \frac{\partial \overline{\mathcal{A}}_{\mathrm{Hxc}}[\boldsymbol{\Lambda}]}{\partial \boldsymbol{\Lambda}^{\dagger}(-\omega_{l})} \right|_{\boldsymbol{\Lambda} = \boldsymbol{\Lambda}(\boldsymbol{\varepsilon})} \right]_{0} = \frac{\mathrm{d}}{\mathrm{d}\varepsilon_{y}(\omega_{m})} \left[\int_{0}^{T} \mathrm{d}t \int \mathrm{d}\mathbf{r} \frac{\delta \overline{E}_{\mathrm{Hxc}}[n_{\Psi(t)}]}{\delta n(\mathbf{r})} \left. \frac{\partial n_{\Psi(t)}(\mathbf{r})}{\partial \boldsymbol{\Lambda}^{\dagger}(-\omega_{l})} \right|_{\boldsymbol{\Lambda} = \boldsymbol{\Lambda}(\boldsymbol{\varepsilon})} \right]_{0}$$

$$= \int_0^T \mathrm{d}t \int \mathrm{d}\mathbf{r} \frac{\delta \overline{E}_{\mathrm{Hxc}}[n_{\Psi_0}]}{\delta n(\mathbf{r})} \frac{\mathrm{d}}{\mathrm{d}\varepsilon_y(\omega_m)} \left[\left. \frac{\partial n_{\Psi(t)}(\mathbf{r})}{\partial \mathbf{\Lambda}^{\dagger}(-\omega_l)} \right|_{\mathbf{\Lambda} = \mathbf{\Lambda}(\boldsymbol{\varepsilon})} \right]_0 \qquad \longleftarrow \text{potential !}$$

$$+ \int_{0}^{T} dt \int d\mathbf{r}' \int d\mathbf{r} \frac{\delta^{2} \overline{E}_{\text{Hxc}}[n_{\Psi_{0}}]}{\delta n(\mathbf{r}') \delta n(\mathbf{r})} \left. \frac{\partial n_{\Psi(t)}(\mathbf{r})}{\partial \mathbf{\Lambda}^{\dagger}(-\omega_{l})} \right|_{0} \left. \frac{\partial n_{\Psi(t)}(\mathbf{r}')}{\partial \varepsilon_{y}(\omega_{m})} \right|_{0}$$
 \times \text{kernel!}

• The "potential" term is simply taken into account with the substitution,

$$\hat{\mathcal{H}} \to \hat{\mathcal{H}} + \int d\mathbf{r} \frac{\delta \overline{E}_{\text{Hxc}}[n_{\Psi_0}]}{\delta n(\mathbf{r})} \hat{n}(\mathbf{r})$$

• Using the expressions $\left. \frac{\partial n_{\Psi(t)}(\mathbf{r}')}{\partial \varepsilon_y(\omega_m)} \right|_0 = \mathrm{i} \sum_p e^{-\mathrm{i}\omega_p t} n^{[1]\dagger}(\mathbf{r}') \left. \frac{\partial \mathbf{\Lambda}(\omega_p)}{\partial \varepsilon_y(\omega_m)} \right|_0$

and
$$\frac{\partial n_{\Psi(t)}(\mathbf{r})}{\partial \mathbf{\Lambda}^{\dagger}(-\omega_l)}\Big|_{0} = -\frac{\mathrm{i}}{2}e^{-\mathrm{i}\omega_l t}n^{[1]}(\mathbf{r}),$$

the "kernel" contribution can be rewritten as follows,

$$\frac{T}{2} \underbrace{\int d\mathbf{r}' \int d\mathbf{r} \frac{\delta^2 \overline{E}_{\text{Hxc}}[n_{\Psi_0}]}{\delta n(\mathbf{r}') \delta n(\mathbf{r})} n^{[1]}(\mathbf{r}) n^{[1]\dagger}(\mathbf{r}')}_{\overline{K}_{\text{Hxc}}} \frac{\partial \mathbf{\Lambda}(-\omega_l)}{\partial \varepsilon_y(\omega_m)} \Big|_{0}$$

 \leftarrow kernel matrix

<u>Conclusion</u>: in the particular case of **wavefunction linear response theory** (no DFT contributions), the linear response equations to be solved are

$$\left(E^{[2]} + \omega_l S^{[2]}\right) \left. \frac{\partial \mathbf{\Lambda}(-\omega_l)}{\partial \varepsilon_y(\omega_m)} \right|_0 = \mathrm{i}\delta(\omega_m + \omega_l) V_y^{[1]}$$

thus leading to

$$\left| \left(E^{[2]} - \omega_l S^{[2]} \right) \frac{\partial \mathbf{\Lambda}(\omega_l)}{\partial \varepsilon_y(\omega_l)} \right|_0 = i V_y^{[1]}$$

and

$$\langle\langle \hat{V}_x; \hat{V}_y \rangle\rangle_{\omega_l} = i V_x^{[1]\dagger} \left. \frac{\partial \mathbf{\Lambda}(\omega_l)}{\partial \varepsilon_y(\omega_l)} \right|_0 = -V_x^{[1]\dagger} \left(E^{[2]} - \omega_l S^{[2]} \right)^{-1} V_y^{[1]}$$

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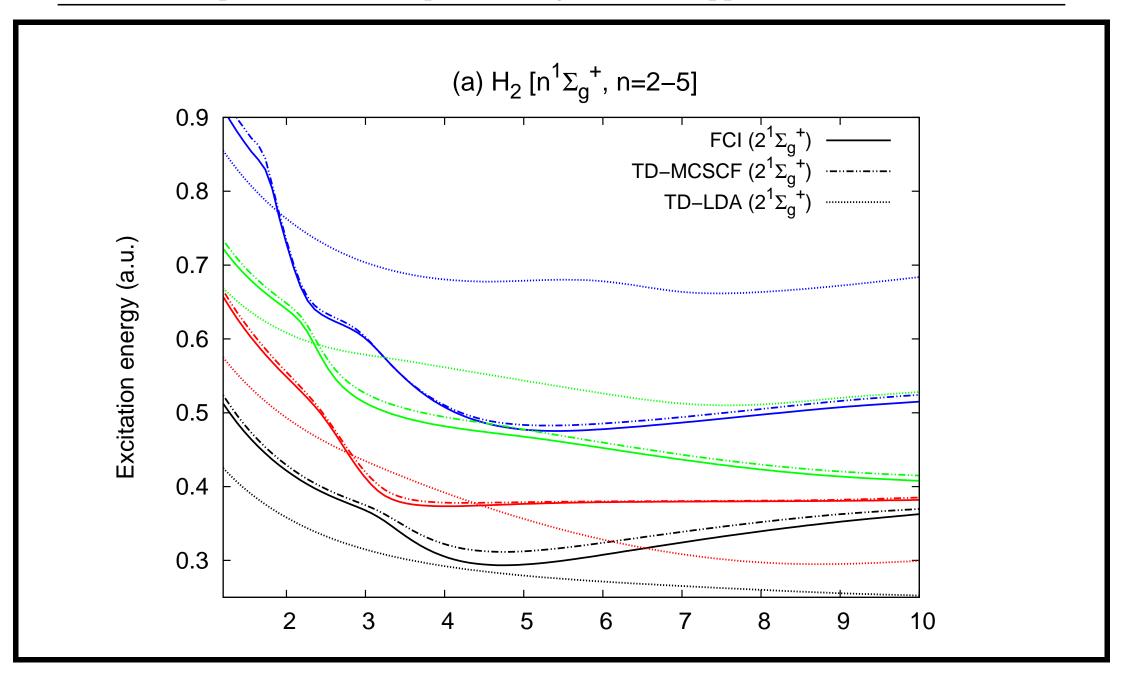
EXERCISE: (1) Show that, in exact response theory, $\Sigma_{ij} = \delta_{ij}$, $\Delta_{ij} = 0$, $A_{ij} = \delta_{ij}(E_i - E_0)$, and $B_{ij} = 0$.

(2) Show that
$$V_x^{[1]} = \begin{bmatrix} \langle \Psi_i | \hat{V}_x | \Psi_0 \rangle \\ -\langle \Psi_0 | \hat{V}_x | \Psi_i \rangle \end{bmatrix}$$

(3) Conclude that

$$\langle \langle \hat{V}_x; \hat{V}_y \rangle \rangle_{\omega} = -\sum_{i>0} \left(\frac{\langle \Psi_0 | \hat{V}_x | \Psi_i \rangle \langle \Psi_i | \hat{V}_y | \Psi_0 \rangle}{E_i - E_0 - \omega} + \frac{\langle \Psi_i | \hat{V}_x | \Psi_0 \rangle \langle \Psi_0 | \hat{V}_y | \Psi_i \rangle}{E_i - E_0 + \omega} \right)$$

Comment: the so-called "density-density response function" (or polarizability) used in Physics is defined as $\chi(\mathbf{r}, \mathbf{r}', \omega) = \langle \langle \hat{n}(\mathbf{r}); \hat{n}(\mathbf{r}') \rangle \rangle_{\omega}$.



Some references

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